# CHEAT **ENGGEN 140**

A concise two-page cheat sheet covering the most essential concepts, formulas, definitions, and examples from ENGGEN 140.

# Page 1: Problem Solving & Modeling

## Problem Solving Framework

1. Define the Problem: Clearly state the problem, including objectives and constraints. 2. Gather Information: Collect relevant data, research, and identify assumptions.

- 3. Generate Solutions: Brainstorm potential
- solutions and evaluate their feasibility.
- 4. Implement and Test: Choose the best solution,
- implement it, and test its effectiveness.

5. Evaluate and Iterate: Analyze the results, identify areas for improvement, and refine the solution.

**Example:** Designing a bridge to withstand specific loads. Defining the problem would involve understanding the required load capacity, environmental conditions, and material constraints.

# Page 2: Data Analysis & Statistics

#### **Descriptive Statistics**

<b>Mean:</b> Average value of a dataset. \bar{x} = \frac{\sum_{i=1}^{n} x_i}{n}	Example: The mean height of students in a class.
<b>Median:</b> Middle value in a sorted dataset.	Example: The median income of households in a city.
Standard Deviation: Measure of data dispersion around the mean. s = \sqrt{\frac{\sum_{i=1}^{n} (x_i - \bar{x})^2}{n-1}}	<b>Example:</b> The standard deviation of test scores indicates the spread of student performance.

#### **Modeling Principles**

Abstraction: Simplifying a complex system by focusing on essential features and ignoring irrelevant details.	<b>Example:</b> Modeling a car's fuel efficiency might involve considering engine size and weight but ignoring the color of the car.
Assumptions: Making informed guesses about aspects of the system that are unknown or too complex to model directly.	<b>Example:</b> Assuming air resistance is negligible when modeling the trajectory of a ball thrown at low speeds.
Validation: Ensuring that the model accurately represents the real-world system and produces reasonable results.	<b>Example:</b> Comparing the model's predicted bridge deflection under load with actual measurements from a physical prototype.

#### Types of Models

Physical Models: Tangible representations of a system (e.g., a scale model of a building). Mathematical Models: Use equations to describe the behavior of a system (e.g., Newton's laws of motion).

Computational Models: Use computer simulations to analyze and predict system behavior (e.g., finite element analysis).

**Example:** A wind tunnel test using a physical model of an airplane wing. A set of differential equations modeling population growth. A computer simulation predicting weather patterns.

### **Probability Distributions**

Normal Distribution: Symmetrical bell-shaped distribution characterized by mean (\mu) and standard deviation (\sigma). Uniform Distribution: All values within a range are equally likely.

Binomial Distribution: Probability of success in a sequence of independent trials.

Example: Heights and weights often follow a normal distribution. Rolling a fair die follows a uniform distribution. The number of heads in 10 coin flips follows a binomial distribution.

#### **Error Analysis**

Consis	<b>natic Error:</b> tent bias in rements.	Example: A miscalibrated measuring instrument.
Unpred	<b>m Error:</b> dictable ations in rements.	<b>Example:</b> Measurement noise due to environmental factors.
	<b>acy:</b> Closeness of surement to the llue.	<b>Precision:</b> Repeatability of a measurement.

