



Getting Started with BeagleBone

Initial Setup

<p>Connecting to BeagleBone:</p> <p>Connect BeagleBone to your computer via USB. It should appear as a network drive.</p>
<p>Accessing via SSH:</p> <p>Use an SSH client (e.g., PuTTY, Terminal) to connect to the BeagleBone. Default IP address is 192.168.7.2. The default username is <code>debian</code> and the password is <code>temppwd</code>.</p>
<p>Updating the System:</p> <p>After logging in, update the system using:</p> <pre>sudo apt update sudo apt upgrade</pre>
<p>Installing Essential Tools:</p> <p>Install essential development tools:</p> <pre>sudo apt install git python3-pip build-essential</pre>
<p>Configuring Network:</p> <p>Edit <code>/etc/network/interfaces</code> to set up static IP address or other network configurations.</p>

Basic Commands

<code>pwd</code>	Print working directory.
<code>ls</code>	List directory contents.
<code>cd</code>	Change directory.
<code>mkdir</code>	Create a new directory.
<code>rm</code>	Remove a file.
<code>nano</code> or <code>vim</code>	Text editors for file editing.

Boot Configuration

<p>U-Boot:</p> <p>BeagleBone uses U-Boot as its bootloader. Configuration files are located in <code>/boot/uEnv.txt</code>.</p>
<p>Kernel Configuration:</p> <p>Kernel parameters can be modified via <code>uEnv.txt</code>. Changes require a reboot.</p>
<p>Device Tree Overlays:</p> <p>Device tree overlays (<code>.dtbo</code>) are used to configure hardware peripherals. Enable overlays by adding lines to <code>uEnv.txt</code>.</p>
<p>Example Overlay Enable:</p> <pre>##Enable I2C1 dt_overlay=BB-I2C1-00A0.dtbo</pre>

GPIO Programming

Accessing GPIO

<p>GPIO Pins:</p> <p>GPIO pins can be accessed via the command line or through programming languages like Python.</p>
<p>Using <code>config-pin</code>:</p> <p><code>config-pin</code> is a utility to configure pin modes.</p> <pre>sudo config-pin p9.12 gpio sudo config-pin p9.12 out</pre>
<p>Checking Pin State:</p> <p>Read the value of the GPIO pin:</p> <pre>cat /sys/class/gpio/gpio60/value</pre>
<p>Finding the GPIO Number:</p> <p>Each pin has a GPIO number associated with it. Use the BeagleBone Black System Reference Manual to find the number.</p>

Python GPIO Control

<p>Installing <code>py-gpio</code>:</p> <p>Install the <code>py-gpio</code> library for Python:</p> <pre>sudo pip3 install py-gpio</pre>
<p>Python Code Example:</p> <pre>import gpio pin = gpio.GPIO(60) # Example GPIO pin pin.export() pin.direction = 'out' pin.value = 1 # Set pin high</pre>
<p>Cleaning Up:</p> <p>Always unexport the pin when done:</p> <pre>pin.unexport()</pre>
<p>Alternative Library - Adafruit BBIO:</p> <p>Another popular library is <code>Adafruit_BBIO</code>. Install with</p> <pre>sudo pip3 install Adafruit_BBIO</pre>

Device Tree Overlays for GPIO

Creating a Custom Overlay:

Create a device tree source (`.dts`) file. This defines the hardware configuration.

Compiling the Overlay:

Use the device tree compiler to create the `.dtbo` file:

```
dtc -O dtb -I dts -o my_overlay.dtbo
my_overlay.dts
```

Example DTS file:

```
/dts-v1/;
/plugin/;

/{
    compatible = "ti,beaglebone-black";

    fragment@0 {
        target = <&am33xx_pinmux>;
        __overlay__ {
            pinctrl_bonnet_gpio:
pinmux_bonnet_gpio {
                pinctrl-single,pins = <0x030
(PIN_OUTPUT_PULLUP | MUX_MODE7)>; /* P9_12,
GPIO1_28 */
            };
        };
    };

    fragment@1 {
        target = <&ocp>;
        __overlay__ {
            bonnet_gpio {
                compatible = "gpio-leds";
            };
        };
    };

    gpios = <&gpio1 28 GPIO_ACTIVE_HIGH>;
        status = "okay";
    };
};
```

Networking

Configuring Network Interfaces

Listing Network Interfaces:

Use `ifconfig` or `ip addr` to list available network interfaces.

Editing `/etc/network/interfaces` :

Manually configure network interfaces by editing

```
/etc/network/interfaces .
```

```
auto eth0
iface eth0 inet static
address 192.168.1.100
netmask 255.255.255.0
gateway 192.168.1.1
dns-nameservers 8.8.8.8 8.8.4.4
```

Using `dhcpcd` :

For dynamic IP configuration, ensure `dhcpcd` is running.

```
sudo systemctl enable dhcpcd
sudo systemctl start dhcpcd
```

Wireless Setup

Connecting to Wi-Fi:

Use `iwconfig` and `wpa_supplicant` to connect to Wi-Fi networks. First, identify wireless interface using

```
iwconfig
```

Configuring `wpa_supplicant` :

Create/edit

```
/etc/wpa_supplicant/wpa_supplicant.conf :
```

```
network={
    ssid="YourNetworkName"
    psk="YourWiFiPassword"
}
```

Bringing up the interface:

```
sudo ifconfig wlan0 up
sudo wpa_supplicant -i wlan0 -c
/etc/wpa_supplicant/wpa_supplicant.conf
sudo dhclient wlan0
```

Firewall Configuration

Using `iptables` :

`iptables` is used for setting up firewall rules. Example: Allowing SSH traffic:

```
sudo iptables -A INPUT -p tcp --dport 22 -j
ACCEPT
```

Saving Rules:

Save iptables rules using `iptables-save` .

Using `ufw` (Uncomplicated Firewall):

A more user-friendly firewall configuration tool:

```
sudo apt install ufw
sudo ufw enable
sudo ufw allow ssh
```

Peripherals and Hardware

I2C Communication

Enabling I2C:

Ensure I2C is enabled in `uEnv.txt` via device tree overlay. Example:

```
dt overlay=BB-I2C1-00A0.dtbo
```

Detecting I2C Devices:

Use `i2cdetect` to scan the I2C bus for connected devices:

```
sudo i2cdetect -y 1
```

Using `i2cget` and `i2cset` :

Read and write to I2C devices using `i2cget` and `i2cset` respectively.

UART Serial Communication

Accessing UART Ports:

UART ports are available as `/dev/tty00`, `/dev/tty01`, etc.

Using `minicom` :

Use `minicom` or `screen` to communicate over UART.

First, install minicom:

```
sudo apt install minicom
```

Then, configure minicom:

```
sudo minicom -s
```

Example `minicom` Configuration:

Set serial device to `/dev/tty01`, baud rate to 115200, and disable hardware flow control.

PWM

Accessing PWM:

PWM functionality is available via device tree overlays.

Enable PWM overlay in `uEnv.txt`.

PWM Control:

Control PWM parameters such as period and duty cycle via `/sys/class/pwm/...`.

Example:

```
echo 1000000 > /sys/class/pwm/pwmchip0/pwm0/period
echo 500000 > /sys/class/pwm/pwmchip0/pwm0/duty_cycle
echo 1 > /sys/class/pwm/pwmchip0/pwm0/enable
```